max. detection range of 30 ft x 30 ft
SAFETY

The device contains IR and visible laser diodes.
IR laser: wavelength 905nm; max. output pulse power 75W (Class 1 according to IEC 60825-1)
Visible laser: wavelength 650nm; max. output CW power 3mW (Class 3R according to IEC 60825-1)

The visible laser beams are inactive during normal operation.
The installer can activate the visible lasers if needed.

CAUTION!
Use of controls, adjustments or performance of procedures other than those specified herein may result in hazardous radiation exposure.

Do not look into the laser emitter or the visible red laser beams.
The warranty is void if unauthorized repairs are made or attempted by unauthorized personnel.
Only trained and qualified personnel may install and adjust the sensor.
Test the proper operation of the installation before leaving the premises.

The installer of the door system is responsible for carrying out a risk assessment and installing the sensor and the door system in compliance with applicable national and international regulations and standards on door safety and if applicable, the machinery directive 2006/42/EC. Other use of the device is outside the permitted purpose and can not be guaranteed by the manufacturer. The manufacturer cannot be held responsible for incorrect installations or inappropriate adjustments of the sensor.

INSTALLATION AND MAINTENANCE

Avoid extreme vibrations.
Do not cover the front screens.
Avoid moving objects and light sources in the detection field.
Avoid the presence of smoke and fog in the detection field.
Avoid condensation.

Avoid exposure to sudden and extreme temperature changes.
Avoid direct exposure to high pressure cleaning.
Do not use aggressive products to clean the front screens.
Wipe the front screens regularly with a clean and damp cloth.
Keep the sensor permanently powered in environments where the temperature can descend below 14°F.
DESCRIPTION

1. laser sweep emission
2. laser sweep reception
3. LED-signals (4)
4. screws for position lock (2)
5. connector
6. protection cover
7. visible laser beams (3)
8. notches for tilt angle adjustment (2)
9. adjustable bracket
10. cable conduits (4)

LED-SIGNAL

1. Detection LED: relay 1 - optional field
2. Detection LED: relay 2 - safety field
3. Error LED
4. Power LED

<table>
<thead>
<tr>
<th>DETECTION LEDS</th>
<th>ERROR LED</th>
<th>POWER LED</th>
</tr>
</thead>
<tbody>
<tr>
<td>detection</td>
<td>error</td>
<td>power</td>
</tr>
<tr>
<td>no detection</td>
<td>no error</td>
<td>no power</td>
</tr>
</tbody>
</table>

LED flashes quickly
LED flashes
LED flashes slowly
LED flashes once
LED is off

All 4 LEDs can be switched off and on again by remote control. This can be useful in cases where the sensor should not draw any attention.

SYMBOLS

Caution! Laser radiation
Remote control sequence
Possible remote control adjustments
Factory values
According to
Not according to
EN ISO 13849-1:2008 CAT 2, PI «d»
The LZR-i30 locks the remote control features out after 30 minutes of idle time. To restore remote control access, cycle power to sensor.

After unlocking, the red LED flashes and the sensor can be adjusted by remote control.

If the red LED flashes quickly after unlocking, you need to enter an access code from 1 to 4 digits.

To end an adjustment session, always lock the sensor.

**ADJUSTING ONE OR MORE PARAMETERS**

**CHECKING A VALUE**

**RESTORING TO FACTORY VALUES**

**SAVING AN ACCESS CODE**

The access code is recommended for sensors installed close to each other.

**DELETING AN ACCESS CODE**

Enter the existing code

=X field width: 13.7 ft

= field width is defined by teach-in

=X = number of flashes = value of the parameter

= teach-in

=X 4X = field width: 13.7 ft

=X 3X = field width is defined by teach-in
1 MOUNTING

1. Use the mounting template to position the sensor correctly. The grey area indicates the detection range. Drill 4 holes and make a hole for the cable.

2. Pass the cable +/- 4 in though the cable opening. If drilling an opening is not possible, use the cable conduits on the back side of the bracket.

3. Position the bracket and fasten the 4 screws firmly in order to avoid vibrations.

4. Open the protection cover, plug the connector and position the cable in the slit. Close the protection cover and fasten it firmly.

5. Position the housing on the bracket and turn the sensor until the two triangles are face to face.

Use the LBA accessory if needed.

2 WIRING

- RED
- BLACK
- WHITE
- GREEN
- WHITE/BLACK
- GREEN/WHITE
- BLUE
- BLUE/WHITE
- ORANGE
- ORANGE/BLACK

POWER SUPPLY
RELAY 1 - OPTIONAL FIELD
RELAY 2 - SAFETY FIELD
TEST
NOT USED

Door control without test: connect blue and blue/white wires to power supply (no polarity).
3 POSITIONING

Unlock the sensor and activate the visible laser beams in order to position the curtains parallel to the door.

The visible laser beams stay activated for 15 minutes or can be turned off by the same sequence.

1 Adjust the lateral position of the detection field.
2 Adjust the tilt angle of the detection field with the hex key.

Lock the position of the mounting bracket to ensure consistent detection.

The distances between the curtains depend on the mounting height and side.

The visible laser beams indicate approximately the position of curtain C1.

The distance between the inner curtains of the 2 sensors shall not exceed 8 in to ensure safety according to EN ISO 13849-1:2008 CAT 2, Pl «d».

18.5 ft
20 in

The sensor memorizes the floor as reference point and signals a fault when its orientation is changed.

No reference point, no signal.

Adjust the lateral position of the detection field.
Adjust the tilt angle of the detection field with the hex key.
Lock the position of the mounting bracket to ensure consistent detection.

The visible laser beams stay activated for 15 minutes or can be turned off by the same sequence.

The distances between the curtains depend on the mounting height and side.

The visible laser beams indicate approximately the position of curtain C1.

The distance between the inner curtains of the 2 sensors shall not exceed 8 in to ensure safety according to EN ISO 13849-1:2008 CAT 2, Pl «d».

18.5 ft
20 in

A teach-in is launched, the sensor learns its environment and automatically determines the detection field(s). Both RED LEDs flash slowly and the 3 visible laser beams automatically light up during 30 seconds.

Ex: After setting the mounting side, the safety and the optional field have the same dimensions.

4 MOUNTING SIDE

Check and select the corresponding mounting side if necessary.

Stay outside of the detection field to avoid disturbances.

left
right

left
right
center

WITH BACKGROUND
The sensor memorizes the floor as reference point and signals a fault when its orientation is changed.

WITHOUT BACKGROUND
No reference point, no signal.

A teach-in is launched, the sensor learns its environment and automatically determines the detection field(s). Both RED LEDs flash slowly and the 3 visible laser beams automatically light up during 30 seconds.

Ex: After setting the mounting side, the safety and the optional field have the same dimensions.
### SAFETY FIELD TEACH-IN

Launch a teach-in after changing the sensor position or when new objects are added to or changed in the detection zone.

During teach-in, the sensor learns and adapts its detection field shape according to its surroundings.

![Diagram showing teach-in process](image)

**FIELD DIMENSIONS**

After the teach-in, the field dimensions can be changed by the remote control.

<table>
<thead>
<tr>
<th>WIDTH</th>
<th>MIN</th>
<th>MAX</th>
</tr>
</thead>
<tbody>
<tr>
<td>no field</td>
<td>20 in</td>
<td>360 in</td>
</tr>
<tr>
<td>Ex: for a field width of 62 in</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>HEIGHT</th>
<th>MIN</th>
<th>MAX</th>
</tr>
</thead>
<tbody>
<tr>
<td>200 in</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

![Diagram showing field dimensions](image)

The default field dimension is limited to 200 in x 200 in. You can adapt the dimensions by remote control, but they can never be bigger than the shape which was defined by the teach-in.
Make sure the white and green wires are connected to the corresponding inputs before configuring the optional field.

**VIRTUAL PUSH BUTTON TEACH-IN (VPB)**

Install 1 or 2 virtual push buttons as activation zone(s) to open the door «manually».

1. Apply the virtual push button sticker(s) **within** the optional field.

2. Launch a VPB teach-in to configure the detection zone(s). When the red LED flashes very slowly after 3 seconds, hold your hand in front of the sticker to learn the detection zone. The green LED flashes 3x to confirm the selection. When the red LED flashes again, learn a second (max. 2) detection zone or wait until the LED switches to green.

Launch a new VPB teach-in each time the sensor position is changed or new objects are added to or changed in the detection zone.

**ATTENTION! This VPB teach-in is different from the safety field teach-in.**

**FIELD DIMENSIONS**

Reduce the field dimensions if needed.

In order to configure the field dimensions, you have to cancel the virtual push button function by launching a new VPB teach-in without any movement in the detection field.

**FACTORY VALUES**

**OPTIONAL FIELD CONFIGURATION (RELAY 1)**

### FIELD DIMENSIONS

<table>
<thead>
<tr>
<th>WIDTH</th>
<th>HEIGHT</th>
</tr>
</thead>
</table>

<table>
<thead>
<tr>
<th>MIN</th>
<th>MAX</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0</td>
<td>0 2 0 - 3 6 0</td>
</tr>
</tbody>
</table>

same as safety field

<table>
<thead>
<tr>
<th>MIN</th>
<th>MAX</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0</td>
<td>0 2 0 - 3 6 0</td>
</tr>
</tbody>
</table>

no field

20 in 360 in 200 in

20 in 360 in 200 in

Change output configuration to suitable applications. see page 9.

Test the good functioning of the installation before leaving the premises.
**ACTIVE DETECTION CURTAINS**

![Diagram of active detection curtains]

The distances between the curtains depend on the mounting height and side. When mounted on the left, the distance between curtain C1 and curtain C4 is approximately 4 in for every 3.25 ft (mounting height). **Example**: at 200 in the distance between C1 and C4 is 20 in.

**IMMUNITY FILTER**

![Diagram of immunity filter]

**FOR CRITICAL ENVIRONMENTS (RAIN, SNOW, FOG)**

- Indoor
- Outdoor low
- Outdoor med
- Outdoor high

**FOR CRITICAL OBJECTS (BLACK CARS)**

- Indoor
- Outdoor low
- Outdoor med
- Outdoor high

Choose between environment or object.

**UNCOVERED ZONE**

![Diagram of uncovered zone]

Increase in case of snow, dead leaves, etc.

**MIN. OBJECT SIZE**

(approximate values)

**OUTPUT ACTIVATION DELAY**

(approximate values)

![Diagram of output activation delay]

The relays are triggered when the detection duration ≥ the selected time.

**DETECTION FIELD REDIRECTION**

**OUTPUT CONFIGURATION**

- R1 Optional Field
  - A - NO
  - P - NC
- R2 Safety Field
  - P - NC
  - A - NO

**FACTORY VALUES**

- R = RELAY OUTPUT
- CAT2 PI d
- CAT2 PI d
# TROUBLESHOOTING

<table>
<thead>
<tr>
<th>Status</th>
<th>Description</th>
<th>Actions</th>
</tr>
</thead>
<tbody>
<tr>
<td>No blue LED</td>
<td>There is no power.</td>
<td>1. Check cable and connexion.</td>
</tr>
<tr>
<td></td>
<td>The polarity of the power supply is inverted.</td>
<td>1. Check the polarity of the power supply.</td>
</tr>
<tr>
<td></td>
<td>All LEDs have been deactivated by remote control.</td>
<td>1. Activate the LEDs by remote control.</td>
</tr>
<tr>
<td>Only the blue LED is on.</td>
<td>The test input is not connected.</td>
<td>1. Check wiring. The BLUE and BLUE/WHITE cable have to be connected to the test input or the power supply.</td>
</tr>
<tr>
<td>The detection LED remains green.</td>
<td>The detection field is too small or deactivated.</td>
<td>1. Check the size of the fields. 2. Launch a teach-in.</td>
</tr>
<tr>
<td>The detection LED remains red.</td>
<td>The object size is too small.</td>
<td>1. Decrease the min. object size.</td>
</tr>
<tr>
<td>The orange LED is flashing and the detection LEDs are red.</td>
<td>No background (reference point) is found.</td>
<td>1. Step out of the field and/or remove the any object(s) from the field and launch a teach in.</td>
</tr>
<tr>
<td>The orange LED is on.</td>
<td>The field is touching the floor, the wall, the door, an object or a person which leads to detection.</td>
<td>1. Activate the 3 red beams and check if the position of the sensor is correct. If not, adjust the hex screws. 2. Verify the field size. 3. Launch a teach-in.</td>
</tr>
<tr>
<td>The sensor does not respond to the remote control.</td>
<td>The sensor is masked.</td>
<td>1. Verify and clean the front screens with a damp cloth.</td>
</tr>
<tr>
<td></td>
<td>The power supply voltage is exceeding the acceptable limits.</td>
<td>1. Check the power supply voltage.</td>
</tr>
<tr>
<td></td>
<td>The sensor exceeds its temperature limits.</td>
<td>1. Verify the outside temperature where the sensor is installed. Eventually protect the sensor from sunlight using a cover.</td>
</tr>
<tr>
<td></td>
<td>Internal error</td>
<td>1. Wait a few seconds. If the LED remains ON, reset the power supply. If the LED turns on again, replace the sensor.</td>
</tr>
<tr>
<td>The sensor does not unlock.</td>
<td>30 minutes after last use of the remote control, the sensor locks the access to the remote control session.</td>
<td>1. Cut and restore power supply. The remote control session is accessible again during 30 minutes.</td>
</tr>
<tr>
<td></td>
<td>The batteries in the remote control are not installed properly or dead.</td>
<td>1. Verify or replace the batteries.</td>
</tr>
<tr>
<td></td>
<td>The remote control is badly pointed.</td>
<td>1. Point the remote control towards the sensor, but with a slight angle. The RC should not be pointed in a right angle in front of the sensor.</td>
</tr>
<tr>
<td></td>
<td>A reflective object is in close proximity to the sensor.</td>
<td>1. Avoid highly reflective material in proximity to the sensor.</td>
</tr>
<tr>
<td>The sensor does not unlock.</td>
<td>You have to enter an access code or the wrong code was entered.</td>
<td>1. Cut and restore power supply. No code is required to unlock during the first minute after powering.</td>
</tr>
</tbody>
</table>
### TECHNICAL SPECIFICATIONS

<table>
<thead>
<tr>
<th>Specification</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Technology:</strong></td>
<td>laser scanner, time-of-flight measurement</td>
</tr>
<tr>
<td><strong>Detection mode:</strong></td>
<td>motion and presence (EN 12453 Typ. E)</td>
</tr>
<tr>
<td><strong>Max. detection range:</strong></td>
<td>30 ft x 30 ft</td>
</tr>
<tr>
<td><strong>Uncovered zone:</strong></td>
<td>2 - 19 in (adjustable)</td>
</tr>
<tr>
<td><strong>Remission factor:</strong></td>
<td>&gt; 2 %</td>
</tr>
<tr>
<td><strong>Angular resolution:</strong></td>
<td>0.3516 °</td>
</tr>
<tr>
<td><strong>Min. detected object size (typ.):</strong></td>
<td>0.8 in @ 118 in ; 1.4 in @ 197 in ; 2.75 in @ 30 ft</td>
</tr>
<tr>
<td><strong>Testbody:</strong></td>
<td>700 mm x 300 mm x 200 mm (testbody A according to EN 12445)</td>
</tr>
<tr>
<td><strong>Emission characteristics:</strong></td>
<td></td>
</tr>
<tr>
<td><strong>IR laser:</strong></td>
<td>wavelength 905 nm; max. output pulse power 75 W (CLASS 1)</td>
</tr>
<tr>
<td><strong>Red visible laser:</strong></td>
<td>wavelength 650 nm; max. output CW power 3 mW (CLASS 3R)</td>
</tr>
<tr>
<td><strong>Supply voltage:</strong></td>
<td>10-35 V DC @ sensor side (to be operated from SELV compatible power supplies only)</td>
</tr>
<tr>
<td><strong>Power consumption:</strong></td>
<td>&lt; 5 W</td>
</tr>
<tr>
<td><strong>Peak current at power-on:</strong></td>
<td>1.8 A (max. 80 ms @ 35 V)</td>
</tr>
<tr>
<td><strong>Cable length:</strong></td>
<td>33 ft</td>
</tr>
<tr>
<td><strong>Response time:</strong></td>
<td>typ. 20 ms; max. 80 ms (+ output activation delay)</td>
</tr>
<tr>
<td><strong>Output:</strong></td>
<td>2 electronic relays (galvanic isolated - polarity free)</td>
</tr>
<tr>
<td><strong>Max. switching voltage:</strong></td>
<td>35 V DC / 24 V AC</td>
</tr>
<tr>
<td><strong>Max. switching current:</strong></td>
<td>80 mA (resistive)</td>
</tr>
<tr>
<td><strong>Switching time:</strong></td>
<td>t_{ON} = 5 ms; t_{OFF} = 5 ms</td>
</tr>
<tr>
<td><strong>Output resistance:</strong></td>
<td>typ 30 Ω</td>
</tr>
<tr>
<td><strong>Voltage drop on output:</strong></td>
<td>&lt; 0.7 V @ 20 mA</td>
</tr>
<tr>
<td><strong>Leakage current:</strong></td>
<td>&lt; 10 μA</td>
</tr>
<tr>
<td><strong>Input:</strong></td>
<td>2 optocouplers (galvanic isolated - polarity free)</td>
</tr>
<tr>
<td><strong>Max. contact voltage:</strong></td>
<td>35 V DC (over-voltage protected)</td>
</tr>
<tr>
<td><strong>Voltage threshold:</strong></td>
<td>Log. H: &gt;8 V DC; Log. L: &lt;3 V DC</td>
</tr>
<tr>
<td><strong>Response time monitoring input:</strong></td>
<td>&lt; 5 ms</td>
</tr>
<tr>
<td><strong>LED-signal:</strong></td>
<td>1 blue LED: power-on status</td>
</tr>
<tr>
<td></td>
<td>1 orange LED: error status</td>
</tr>
<tr>
<td></td>
<td>2 bi-coloured LEDs: detection/output status (green: no detection; red: detection)</td>
</tr>
<tr>
<td><strong>Dimensions:</strong></td>
<td>5.0 in (D) x 3.6 in (W) x 2.75 in (H) (mounting bracket + 0.55 in)</td>
</tr>
<tr>
<td><strong>Material:</strong></td>
<td>PC/ASA</td>
</tr>
<tr>
<td><strong>Colour:</strong></td>
<td>black or white</td>
</tr>
<tr>
<td><strong>Mounting angles on bracket:</strong></td>
<td>-45 °, 0 °, 45 °</td>
</tr>
<tr>
<td><strong>Rotation angles on bracket:</strong></td>
<td>-5 ° to +5 ° (lockable)</td>
</tr>
<tr>
<td><strong>Tilt angles on bracket:</strong></td>
<td>-3 ° to +3 °</td>
</tr>
<tr>
<td><strong>Protection degree:</strong></td>
<td>IP65</td>
</tr>
<tr>
<td><strong>Temperature range:</strong></td>
<td>-22 °F to +140 °F if powered; +14 °F to +140 °C unpowered</td>
</tr>
<tr>
<td><strong>Humidity:</strong></td>
<td>0-95 % non-condensing</td>
</tr>
<tr>
<td><strong>Vibrations:</strong></td>
<td>&lt; 2 G</td>
</tr>
<tr>
<td><strong>Pollution on front screens:</strong></td>
<td>max. 30 %; homogenous</td>
</tr>
<tr>
<td><strong>Expected lifetime:</strong></td>
<td>20 years</td>
</tr>
</tbody>
</table>

Specifications are subject to changes without prior notice. All values measured in specific conditions.
BEA hereby declares that the LZR®-I100/-I110 is in conformity with the basic requirements and the other relevant provisions of the directives 2006/95/EC, 2002/95/EC, 2004/108/EC and 2006/42/EC.

Notified Body for EC inspection: 0044 - TÜV NORD CERT GmbH, Langemarckstr. 20, 45141 D-Essen

EC-type examination certificate number: 44 205 11 392410-002

Angleur, May 2011

Jean-Pierre Valkenberg, Authorized representative and responsible for technical documentation

The complete declaration of conformity is available on our website: www.bea-industrial.be

For EC countries: according to the directive 2012/19/EU for Waste Electrical and Electronic Equipment (WEEE)